

# Investigation of holomorphic functions on the bidisk via operator theory

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# Schur functions

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A function  $\varphi \in \mathcal{S}_1$  is well-behaved on the interior of the disk  $\mathbb{D}$ .  
What about at the edge?

# Studying Schur functions

## Question

*How do Schur functions behave on the boundary of the unit circle  $\mathbb{T}$ ? When do derivatives exist at boundary points  $\tau \in \mathbb{T}$ ? Is there any structure to the derivatives at boundary points?*

These questions are typical of functional analysis, which studies classes of functions.

# A useful difference quotient

We are interested in the existence of limits and derivatives at boundary points. So we define a difference quotient that examines when the function stays under control near the boundary:

## Definition

The **Julia quotient** for a function  $\varphi \in \mathcal{S}_1$  is the ratio

$$J_\varphi(\lambda) = \frac{1 - |\varphi(\lambda)|}{1 - |\lambda|}.$$

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Let  $\varphi \in \mathcal{S}_1$ . A point  $\tau \in \mathbb{T}$  is a **carapoint** for  $\varphi$  if there exists a sequence  $\{\lambda_n\} \subset \mathbb{D}$  tending to  $\tau$  such that

$$J_\varphi(\lambda_n) = \frac{1 - |\varphi(\lambda_n)|}{1 - |\lambda_n|}$$

is bounded.

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- a set  $S$  approaches  $\tau \in \mathbb{T}$  nontangentially if  $S$  is contained in a wedge with a point at  $\tau$ .
- A sequence  $\{\lambda_n\} \subset S$  tends to  $\tau$  nontangentially if  $\lim_{n \rightarrow \infty} \lambda_n = \tau$  and  $\{\lambda_n\}$  is a nontangential set at  $\tau$ . We write  $\lambda \xrightarrow{\text{nt}} \tau$  to indicate a non-tangential limit.

# Julia-Carathéodory Theorem

## Theorem (Julia, Carathéodory)

*Let  $\varphi$  a nonconstant Schur function, i.e.  $\varphi$  is holomorphic and  $\varphi : \mathbb{D} \rightarrow \mathbb{D}$ . Let  $\tau$  be a point in  $\mathbb{T}$ . The following are equivalent:*

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A  $\tau$  is a carapoint for  $\varphi$ ;

B for every sequence  $\{\lambda_n\} \xrightarrow{\text{nt}} \tau$ ,  $J_\varphi(\lambda_n)$  is bounded;

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- A  $\tau$  is a carapoint for  $\varphi$ ;
- B for every sequence  $\{\lambda_n\} \xrightarrow{\text{nt}} \tau$ ,  $J_\varphi(\lambda_n)$  is bounded;
- C there exists  $\varphi(\tau) \in \mathbb{T}$  such that  $\varphi(\tau) = \lim_{\lambda \xrightarrow{\text{nt}} \tau} \varphi(\lambda)$ ,

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- A  $\tau$  is a carapoint for  $\varphi$ ;
- B for every sequence  $\{\lambda_n\} \xrightarrow{\text{nt}} \tau$ ,  $J_\varphi(\lambda_n)$  is bounded;
- C there exists  $\varphi(\tau) \in \mathbb{T}$  such that  $\varphi(\tau) = \lim_{\lambda \xrightarrow{\text{nt}} \tau} \varphi(\lambda)$ , and furthermore,  $\varphi$  is nontangentially differentiable at  $\tau$ , i.e. there exists  $\varphi'(\tau) \in \mathbb{T}$  such that, as  $\lambda \xrightarrow{\text{nt}} \tau$ ,

$$\varphi(\lambda) = \varphi(\tau) + \varphi'(\tau)(\lambda - \tau) + o(|\lambda - \tau|).$$

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C  $\varphi$  is nontangentially differentiable at  $\tau$ , i.e. there exists  $\varphi(\tau), \varphi'(\tau) \in \mathbb{T}$  such that, as  $\lambda \xrightarrow{\text{nt}} \tau$ ,

$$\varphi(\lambda) \cong \varphi(\tau) + \varphi'(\tau)(\lambda - \tau) \quad .$$



## A comment and a question

First, a comment on what the J-C Theorem says: as long as  $\varphi(\lambda)$  doesn't run away too quickly towards the boundary as the input  $\lambda$  approaches  $\tau$ ,  $\varphi$  is nice near  $\tau$  in the sense that it has a linear approximation on nontangential sets.

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## Question

*Is this theorem true in two variables? What would it have to say?*

# Conjecture

If a two variable Schur function  $\varphi$  is controlled by a growth condition near a boundary point  $\tau$ , then  $\varphi$  is nicely behaved on nontangential sets near  $\tau$ .

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## Two variables

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The distinguished boundary of  $\mathbb{D}^2$  is  $\mathbb{T}^2 = \mathbb{T} \times \mathbb{T}$ , the unit 2-torus. We write  $\tau = (\tau^1, \tau^2)$  for the components with  $|\tau^i| = 1$  ( $\mathbb{T}^2$  is where the interesting function theory occurs.)

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The *Schur class in two variables*  $\mathcal{S}_2$  is the family of holomorphic functions from  $\mathbb{D}^2$  to  $\mathbb{D}^-$ .

## Definition

The **Julia quotient** for a function  $\varphi \in \mathcal{S}_2$  is the ratio

$$J_\varphi(\lambda) = \frac{1 - |\varphi(\lambda)|}{1 - \max\{|\lambda^1|, |\lambda^2|\}}.$$



## Definition

Let  $\varphi \in \mathcal{S}_2$ . A point  $\tau \in \mathbb{T}^2$  is a **carapoint** for  $\varphi$  if there exists a sequence  $\{\lambda_n\} = \{(\lambda_n^1, \lambda_n^2)\} \subset \mathbb{D}^2$  tending to  $\tau$  such that

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If  $\varphi \in \mathcal{S}_2$  has a carapoint at  $\tau$ , then  $\varphi$  has a linear approximation on nontangential sets near  $\tau$ .

# A speculation on the bidisk

## Speculation

*Let  $\varphi \in \mathcal{S}_2$ . If  $\tau \in \mathbb{T}^2$  is a carapoint for  $\varphi$ , then  $\varphi$  is nontangentially differentiable at  $\tau$ , i.e. there exist a nontangential limit  $\varphi(\tau) \in \mathbb{T}$  and a gradient  $\nabla\varphi(\tau)$  such that*

$$\varphi(\lambda) = \varphi(\tau) + \nabla\varphi(\tau) \cdot (\lambda - \tau) + o(\|\lambda - \tau\|)$$

*as  $\lambda \xrightarrow{\text{nt}} \tau$ .*

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(Fundamental theorem of algebra)
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On the other hand,

- In two variables, polynomials **rarely** factor into linear terms.  
(even worse in more than two variables)
- In two variables, the zeroes of polynomials are **never** isolated.

# A simple rational function

## Example

Let  $\varphi$  be the rational inner function

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BUT  $\varphi$  does NOT have a linear approximation near  $\chi$ .

# Directional derivatives

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That is, the directional derivative of  $\varphi$  at  $\chi$  in the direction  $-\delta$ ,

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$$D_{-\delta}\varphi(\chi) = -\frac{2\delta_1\delta_2}{\delta_1 + \delta_2}.$$

# Need a new tool

## Question

*Does this always happen? Does  $\varphi$  have a carapoint at  $\tau$  if and only if  $\varphi$  directionally differentiable at  $\tau$ ? Does a function ever have a linear approximation at a carapoint?*

To answer these questions, we use a tool that allows us to avoid dealing with the function and instead analyze the geometry of vectors.

# Hilbert spaces

A Hilbert space is an infinite dimensional analogue of a vector space. Hilbert spaces come equipped with inner products, orthogonality, and linear operators, the familiar tools of vector spaces.

In the early 1990s, J. Agler, following work of D. Sarason, invented the notion of a **Hilbert space model**, a tool for transforming questions about an analytic function into questions about inner products of vectors.

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- $u$  is an analytic map  $u : \mathbb{D}^2 \rightarrow \mathcal{M}$

such that the model equation

$$1 - \overline{\varphi(\mu)}\varphi(\lambda) = \left\langle \left(1 - \mu^*\lambda\right)u(\lambda), u(\mu) \right\rangle_{\mathcal{M}}$$

holds for all  $\lambda, \mu \in \mathbb{D}^2$  where  $\lambda$  is an operator from  $\mathbb{D}^2$  into  $\mathcal{L}(\mathcal{M})$  by

$$\lambda = \lambda^1 P + \lambda^2 (1 - P),$$

where  $P$  is a projection operator onto the space  $\mathcal{M}_1$ .

# J-C Theorem on the bidisk

Hilbert space models can be used to give a two-variable J-C Theorem:

Theorem (Agler, M<sup>C</sup>Carthy, Young, 2012)

Let  $\varphi$  be in  $\mathcal{S}_2$ ,  $\tau \in \mathbb{T}^2$ .

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- b  $\lim_{\lambda \xrightarrow{\text{n.t.}} \tau} \varphi(\lambda) = \varphi(\tau) \in \mathbb{T}$  and  $\varphi$  is directionally differentiable for all directions  $-\delta$  pointing into the bidisk at  $\tau$ ;

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- c for any model  $(\mathcal{M}, u)$  of  $\varphi$ , the map  $u(\lambda)$  is bounded on all sequences  $\lambda \xrightarrow{\text{nt}} \tau$ .

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- c for any model  $(\mathcal{M}, u)$  of  $\varphi$ , the map  $u(\lambda)$  is bounded on all sequences  $\lambda \xrightarrow{\text{nt}} \tau$ .

**2**  $\varphi$  is nontangentially differentiable at  $\tau$  if and only if for every model  $(\mathcal{M}, u)$  for  $\varphi$ , the map  $u(\lambda)$  extends continuously to  $\tau$  on nontangential sets.

# What does it mean?

The two variable Julia-Carathéodory Theorem shows that a function can be linearly approximated at a carapoint precisely when Hilbert space models are continuous at that point (in the sense that  $\lim_{\lambda \xrightarrow{\text{nt}} \tau} u(\lambda) = u(\tau)$ ).

How do boundary singularities points play a role in this?

# Singularities and differentiability

## Example

$$\varphi(\lambda) = \frac{\lambda^1 + \lambda^2 - 2\lambda^1\lambda^2}{2 - \lambda^1 - \lambda^2}$$

has a singularity at  $\chi = (1, 1)$  and is NOT nontangentially differentiable.

We might conjecture that this is always the case.

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## Example

$$f(\lambda) = \frac{-4\lambda^1(\lambda^2)^2 + (\lambda^2)^2 + 3\lambda^1\lambda^2 - \lambda^1 + \lambda^2}{(\lambda^2)^2 - \lambda^1\lambda^2 - \lambda^1 - 3\lambda^2 + 4}$$

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# A more general model

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The model operator  $\lambda = \lambda_1 P + \lambda_2(1 - P)$  is linear and does not share the singularity.

As a consequence, the Hilbert space  $\mathcal{M}$  encodes the noise from the singular behavior instead of the operator  $\lambda$ , and the resulting space is too large.

# Modeling singular carapoints

Let  $Y$  be an operator on a Hilbert space  $\mathcal{M}$  that is a positive contraction. (By way of analogy, think of  $Y$  as a square matrix with eigenvalues in the interval  $[0, 1]$ ).

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Consider the function  $I_Y(\lambda) : \mathbb{C}^2 \rightarrow \mathcal{L}(\mathcal{M})$  defined by

$$I_Y(\lambda) = \frac{\lambda^1 Y + \lambda^2 (1 - Y) - \lambda^1 \lambda^2}{1 - \lambda^1 (1 - Y) - \lambda^2 Y}.$$

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- $I_Y$  is an operator-valued contractive map (like a Schur function).
- $I_Y$  has a singular carapoint at  $\chi$ .
- $I_Y(\chi) = I_{\mathcal{M}}$ .

## Use $I_Y$ in a model

So the idea is to use  $I_Y$ , which has a singular carapoint at  $\chi$ , to model a general  $\varphi$  with a singular carapoint at  $\chi$ .

## Use $I_Y$ in a model

So the idea is to use  $I_Y$ , which has a singular carapoint at  $\chi$ , to model a general  $\varphi$  with a singular carapoint at  $\chi$ .

That is, replace  $(1 - \mu^* \lambda)$  with  $(1 - I_Y(\mu)^* I_Y(\lambda))$  in the model.

# A generalized Hilbert space model

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such that the equation

$$1 - \overline{\varphi(\mu)}\varphi(\lambda) = \left\langle \left(1 - I(\mu)^* I(\lambda)\right) u(\lambda), u(\mu) \right\rangle$$

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holds for all  $\lambda, \mu \in \mathbb{D}^2$  where  $I_Y(\lambda)$  is the operator valued map

$$I_Y(\lambda) = \frac{\lambda^1 Y + \lambda^2 (1 - Y) - \lambda^1 \lambda^2}{1 - \lambda^1 (1 - Y) - \lambda^2 Y},$$

where  $Y$  is a positive contraction on  $\mathcal{M}$ .



# Generalized models are continuous at carapoints

Theorem (T.D., '16 and Agler, T.D., Young, '12)

*Let  $\varphi \in \mathcal{S}_2$ .  $\chi = (1, 1)$  is a carapoint for  $\varphi \in \mathcal{S}_2$  if and only if there exists a generalized model  $(\mathcal{M}, u, I)$  of  $\varphi$  such that  $u$  extends continuously to  $\chi$  on nontangential sets.*

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That is, we can always find a model function  $u(\lambda)$  in a generalized model that extends continuously to the boundary. In other words, it makes sense to write

$$\lim_{\lambda \xrightarrow{\text{nt}} \chi} u(\lambda) = u(\chi).$$

We can use  $u$  to probe the behavior of  $\varphi$  at a singular carapoint.

# A model argument

We calculate the directional derivative of  $\varphi$  at a carapoint  $\chi$  in the direction  $-\delta$ : see board.

# Slope functions

A Pick function is an analytic function from the complex upper halfplane into itself.

Theorem (Agler, McCarthy, Young and Agler, T.D., Young)

*Suppose that  $\varphi \in \mathcal{S}_2$  has a carapoint at  $\chi$ . Let  $-\delta$  be any direction pointing into the bidisk at  $\chi$ . Then there exists a function  $h$  so that  $h$  and  $-zh$  are in the Pick class so that*

$$D_{-\delta}\varphi(\chi) = -\varphi(\chi)\delta_2 h\left(\frac{\delta_2}{\delta_1}\right)$$

# Singular points and differentiability

We have yet to answer our last question: how can we tell the difference between singular carapoints that give rise to linear approximations and those that give rise merely to directional derivatives?

Theorem (T.D., 16)

*Let  $\varphi \in \mathcal{S}_2$  have a carapoint at  $\chi$ .  $u(\chi) \perp \ker Y(1 - Y)$  if and only if  $\varphi$  is nontangentially differentiable at  $\chi$ .*

Theme: model geometry  $\Leftrightarrow$  function theory

Thank you.

- 1 J. Agler, J.E. McCarthy, and N.J. Young. A Carathéodory theorem for the bidisk using Hilbert space methods. *Math. Ann.*, 352:581-624, 2012.
- 2 J. Agler, R. Tully-Doyle, N.J. Young. Boundary behavior of analytic functions of two variables via generalized models. *Indag. Math.*, 23:995-1027, 2012. (see on ArXiv).
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